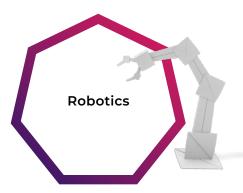




## **Activity sheet 1**

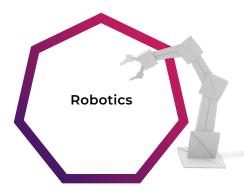


What complex actions might an industrial robot carry out?  Why do speed and precision matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
Why do speed and precision matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
Why do <b>speed</b> and <b>precision</b> matter in industry?
What <b>programming</b> might a robot require?
How might a robot avoid the need for <b>human intervention</b> ?



## 2

## Activity sheet 2

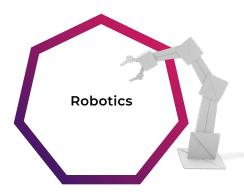


What features allow a robot to <b>move</b> ?
What features allow a robot to <b>manipulate</b> an object?
What features would allow a robot to <b>process</b> an object?
What features would provide the robot with <b>information</b> about its position, state and environment?





## Activity sheet 3



Give examples of how linear and rotation	al
joints might be used in robotics.	

Advantages of robotics:

Limitations of robotics:

Give some examples of how sensors might be used in robotics.

List some tools an end effector might use.